

## LTC2850/LTC2851/LTC2852

## 3.3V 20Mbps RS485/RS422 Transceivers

#### **FEATURES**

- 3.3V Supply Voltage
- 20Mbps Maximum Data Rate
- No Damage or Latchup Up to ±15kV HBM
- High Input Impedance Supports 256 Nodes (C-, I-Grade)
- Operation Up to 125°C (H-Grade)
- Guaranteed Failsafe Receiver Operation Over the Entire Common Mode Range
- Current Limited Drivers and Thermal Shutdown
- Delayed Micropower Shutdown: 5μA Maximum (C-, I-Grade)
- Power Up/Down Glitch-Free Driver Outputs
- Low Operating Current: 370µA Typical in Receive Mode
- Compatible with TIA/EIA-485-A Specifications
- Available in 8-Pin and 10-Pin 3mm × 3mm DFN, 8-Pin and 10-Pin MSOP, and 8-Pin and 14-Pin SO Packages

#### **APPLICATIONS**

- Low Power RS485/RS422 Transceiver
- Level Translator
- Backplane Transceiver

#### DESCRIPTION

The LTC®2850, LTC2851 and LTC2852 are low power, 20Mbps RS485/RS422 transceivers operating on 3.3V supplies. The receiver has a one-eighth unit load supporting up to 256 nodes per bus (C-, I-grade), and a failsafe feature that guarantees a high output state under conditions of floating or shorted inputs.

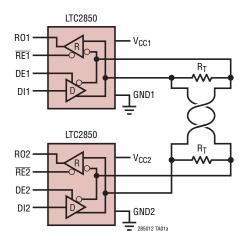
The driver maintains a high output impedance over the entire common mode range when disabled or when the supply is removed. Excessive power dissipation caused by bus contention or a fault is prevented by current limiting all outputs and by thermal shutdown.

Enhanced ESD protection allows these parts to withstand up to  $\pm 15$ kV (human body model) on the transceiver interface pins without latchup or damage.

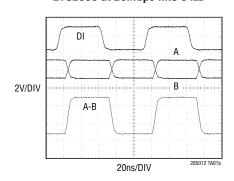
PART NUMBER	DUPLEX	PACKAGE
LTC2850	Half	SO-8, MSOP-8, DFN-8
LTC2851	Full	SO-8, MSOP-8, DFN-8
LTC2852	Full	SO-14, MSOP-10, DFN-10

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### TYPICAL APPLICATION



#### LTC2850 at 20Mbps Into $54\Omega$

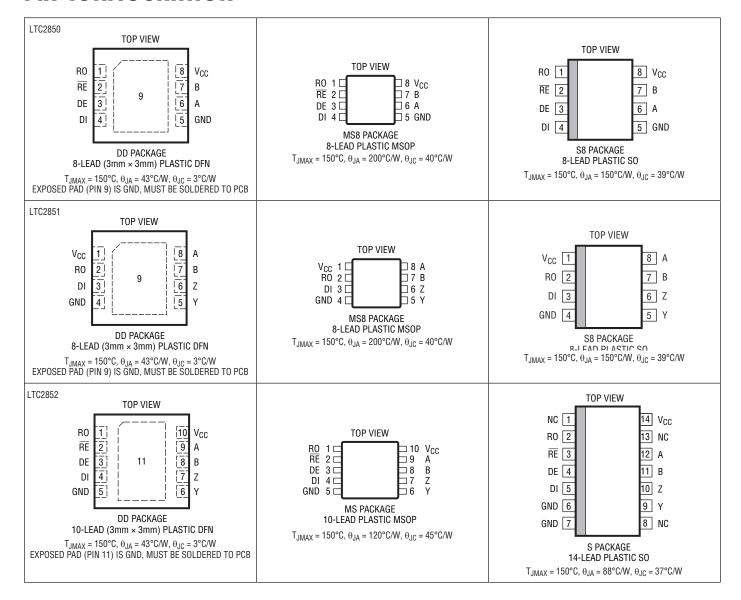


## **ABSOLUTE MAXIMUM RATINGS** (Note 1)

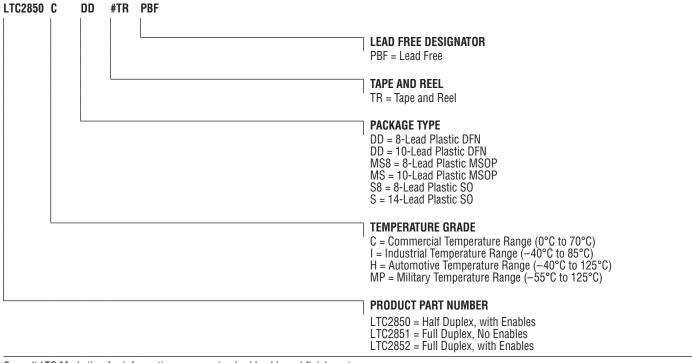
Supply Voltage (V <sub>CC</sub> )	0.3V to 7V
Logic Input Voltages (RE, DE, D	OI)0.3V to 7V
Interface I/O:	
A, B, Y, Z	$(V_{CC} - 15V)$ to 15V
Receiver Output Voltage (RO)	0.3V to $(V_{CC} + 0.3V)$

Operating Temperature (Note 4)	
LTC285xC	0°C to 70°C
LTC285xl	40°C to 85°C
LTC285xH	40°C to 125°C
LTC285xMP	55°C to 125°C
Storage Temperature Range	65°C to 150°C
Lead Temperature (Soldering, 10 sec)	
MSOP	300°C

#### PIN CONFIGURATION



#### ORDER INFORMATION



Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/ For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/

### PRODUCT SELECTION GUIDE

PART NUMBER	PART MARKING	DUPLEX	LOW POWER SHUTDOWN MODE	PACKAGE
LTC2850	2850/I/H, LTCQD, LCQC	Half	Yes	SO-8, MSOP-8, DFN-8
LTC2851	2851/I/H, LTCWF, LCWD	Full	No	SO-8, MSOP-8, DFN-8
LTC2852	2852CS/IS/HS, LTCRX, LCRY	Full	Yes	SO-14, MSOP-10, DFN-10
LTC2850MP	2850MP, LTFYD, LFYC	Half	Yes	SO-8, MSOP-8, DFN-8
LTC2851MP	2851MP, LTFYG, LFYF	Full	No	SO-8, MSOP-8, DFN-8
LTC2852MP	2852MPS, LTFYH, LFYJ	Full	Yes	S0-14, MSOP-10, DFN-10



# **ELECTRICAL CHARACTERISTICS** The $\bullet$ denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25\,^{\circ}\text{C}$ . $V_{CC} = 3.3V$ , unless otherwise noted. (Note 2)

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Driver							
V <sub>OD</sub>	Differential Driver Output Voltage	$\begin{array}{l} R=\infty,V_{CC}=3V\;(Figure\;1)\\ R=27\Omega,V_{CC}=3V\;(Figure\;1)\\ R=50\Omega,V_{CC}=3.13V\;(Figure\;1) \end{array}$	•	1.5 2		V <sub>CC</sub> V <sub>CC</sub> V <sub>CC</sub>	V V
Δ V <sub>OD</sub>	Difference in Magnitude of Driver Differential Output Voltage for Complementary Output States	R = $27\Omega$ or $50\Omega$ (Figure 1)	•			0.2	V
V <sub>OC</sub>	Driver Common Mode Output Voltage	R = 27 $\Omega$ or 50 $\Omega$ (Figure 1)	•			3	V
$\Delta  V_{OC} $	Difference in Magnitude of Driver Common Mode Output Voltage for Complementary Output States	R = $27\Omega$ or $50\Omega$ (Figure 1)	•			0.2	V
I <sub>OZD</sub>	Driver Three-State (High Impedance) Output Current on Y and Z	DE = 0V, (Y or Z) = -7V, 12V (LTC2852) H-Grade	•			±10 ±50	μA μA
I <sub>OSD</sub>	Maximum Driver Short-Circuit Current	$-7V \le (Y \text{ or } Z) \le 12V \text{ (Figure 2)}$	•	-250	±180	±250 300	mA mA
Receiver							
I <sub>IN</sub>	Receiver Input Current (A, B)	DE = TE = 0V, $V_{CC}$ = 0V or 3.3V, $V_{IN}$ = 12V (Figure 3) (C, I-Grade) DE = TE = 0V, $V_{CC}$ = 0V or 3.3V, $V_{IN}$ = -7V, (Figure 3) (C, I-Grade)	•	-100		125	µА µА
		DE = TE = 0V, $V_{CC}$ = 0V or 3.3V, $V_{IN}$ = 12V (Figure 3) (H-Grade) DE = TE = 0V, $V_{CC}$ = 0V or 3.3V, $V_{IN}$ = -7V, (Figure 3) (H-Grade)	•	-145		250	μА
R <sub>IN</sub>	Receiver Input Resistance	$\overline{RE} = V_{CC} \text{ or } 0V, DE = TE = 0V,$ $V_{IN} = -7V, -3V, 3V, 7V, 12V \text{ (Figure 3)}$ (C, I-Grade)	•	96	125		kΩ
		$\overline{RE} = V_{CC}$ or 0V, DE = TE = 0V, $V_{IN} = -7V, -3V, 3V, 7V, 12V$ (Figure 3) (H-Grade)	•	48	125		kΩ
$V_{TH}$	Receiver Differential Input Threshold Voltage	-7V ≤ B ≤ 12V	•			±0.2	V
$\Delta V_{TH}$	Receiver Input Hysteresis	B = 0V			25		mV
$\overline{V_{OH}}$	Receiver Output High Voltage	I(R0) = -4mA, A-B = 200mV, V <sub>CC</sub> = 3V	•	2.4			V
$\overline{V_{0L}}$	Receiver Output Low Voltage	I(RO) = 4mA, A-B = -200mV, V <sub>CC</sub> = 3V	•			0.4	V
I <sub>OZR</sub>	Receiver Three-State (High Impedance) Output Current on RO	$\overline{RE} = V_{CC}$ , $0V \le RO \le V_{CC}$ (LTC2850, LTC2852)	•			±1	μА
I <sub>OSR</sub>	Receiver Short-Circuit Current	$0V \le RO \le V_{CC}$	•			±85	mA
Logic							
V <sub>IH</sub>	Logic Input High Voltage	V <sub>CC</sub> = 3.6V	•	2			V
V <sub>IL</sub>	Logic Input Low Voltage	V <sub>CC</sub> = 3V	•			0.8	V
I <sub>INL</sub>	Logic Input Current		•		0	±10	μA

## **ELECTRICAL CHARACTERISTICS** The $\bullet$ denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$ . $V_{CC} = 3.3V$ , unless otherwise noted. (Note 2)

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Supplies							
I <sub>CCS</sub>	Supply Current in Shutdown Mode	DE = 0V, RE = V <sub>CC</sub> , LTC2850, LTC2852 (C and I-Grade)	•		0	5	μА
		LTC2850, LTC2852 (H-Grade)	•		0	15	μA
I <sub>CCR</sub>	Supply Current in Receive Mode	DE = 0V, RE = 0V (LTC2850, LTC2852)	•		370	900	μА
I <sub>CCT</sub>	Supply Current in Transmit Mode	No Load, DE = $V_{CC}$ , $\overline{RE}$ = $V_{CC}$ (LTC2850, LTC2852)	•		450	1000	μА
I <sub>CCTR</sub>	Supply Current with Both Driver and Receiver Enabled	No Load, DE = $V_{CC}$ , $\overline{RE}$ = 0V	•		450	1000	μА

## **SWITCHING CHARACTERISTICS** The ullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25 \,^{\circ}\text{C}$ . $V_{CC} = 3.3V$ , unless otherwise noted. (Note 2)

PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Maximum Data Rate	(Note 3)	•	20			Mbps
Driver Input to Output	$R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)	•		10	50	ns
Driver Input to Output Difference  t <sub>PLHD</sub> - t <sub>PHLD</sub>	$R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)	•		1	6	ns
Driver Output Y to Output Z	$R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)	•		1	±6	ns
Driver Rise or Fall Time	$R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)	•		4	12.5	ns
Driver Enable or Disable Time	$R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = 0V$ (Figure 5) (LTC2850, LTC2852)	•			70	ns
Driver Enable from Shutdown	$R_L$ = 500 $\Omega$ , $C_L$ = 50pF, $\overline{RE}$ = $V_{CC}$ (Figure 5) (LTC2850, LTC2852)	•			8	μs
Time to Shutdown	$R_L = 500\Omega$ , $C_L = 50pF$ , $(DE = \downarrow$ , $\overline{RE} = V_{CC})$ or $(DE = 0V$ , $\overline{RE} = \uparrow$ ) (Figure 5) (LTC2850, LTC2852)	•			100	ns
	·					
Receiver Input to Output	$C_L = 15 pF, V_{CM} = 1.5 V,  V_{AB}  = 1.5 V, t_R \text{ and } t_F < 4 ns \text{ (Figure 6)}$	•		50	70	ns
Differential Receiver Skew  t <sub>PLHR</sub> - t <sub>PHLR</sub>	C <sub>L</sub> = 15pF (Figure 6)	•		1	6	ns
Receiver Output Rise or Fall Time	C <sub>L</sub> = 15pF (Figure 6)	•		3	12.5	ns
Receiver Enable/Disable	$R_L$ =1k, $C_L$ =15pF, DE = $V_{CC}$ (Figure 7) (LTC2850, LTC2852)	•			50	ns
Receiver Enable from Shutdown	R <sub>L</sub> = 1k, C <sub>L</sub> = 15pF, DE = 0V (Figure 7) (LTC2850, LTC2852)	•			8	μs
	Maximum Data Rate  Driver Input to Output  Driver Input to Output Difference   tplhd - tphld  Driver Output Y to Output Z  Driver Rise or Fall Time  Driver Enable or Disable Time  Driver Enable from Shutdown  Time to Shutdown  Receiver Input to Output  Differential Receiver Skew   tplhg - tphlg  Receiver Output Rise or Fall Time  Receiver Enable/Disable	Maximum Data Rate       (Note 3)         Driver Input to Output $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)         Driver Input to Output Difference $ t_{PLHD} - t_{PHLD} $ $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)         Driver Output Y to Output Z $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)         Driver Rise or Fall Time $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)         Driver Enable or Disable Time $R_L = 500\Omega$ , $C_L = 50pF$ , $RE = 0V$ (Figure 5) (LTC2850, LTC2852)         Driver Enable from Shutdown $R_L = 500\Omega$ , $C_L = 50pF$ , $RE = V_{CC}$ (Figure 5) (LTC2850, LTC2852)         Time to Shutdown $R_L = 500\Omega$ , $C_L = 50pF$ , $RE = V_{CC}$ (Figure 5) (LTC2850, LTC2852)         Receiver Input to Output $C_L = 15pF$ , $V_{CM} = 1.5V$ , $V_{AB} = 1$	Maximum Data Rate       (Note 3)       ●         Driver Input to Output $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)       ●         Driver Input to Output Difference $ t_{PLHD} - t_{PHLD} $ $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)       ●         Driver Output Y to Output Z $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)       ●         Driver Rise or Fall Time $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4)       ●         Driver Enable or Disable Time $R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = 0V$ (Figure 5)       ●         Driver Enable from Shutdown $R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = V_{CC}$ (Figure 5)       ●         Time to Shutdown $R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = V_{CC}$ (Figure 5)       ●         Time to Shutdown $R_L = 500\Omega$ , $C_L = 50pF$ , $\overline{RE} = V_{CC}$ (Figure 5)       ●         Receiver Input to Output $C_L = 15pF$ , $V_{CM} = 1.5V$ , $ V_{AB}  = 1.5V$ ,	Maximum Data Rate (Note 3) • 20  Driver Input to Output $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 4) • $R_{DIFF} = 54\Omega$ , $C_L = 100pF$ (Figure 5) (LTC2850, LTC2850, LTC2852)  Time to Shutdown $R_L = 500\Omega$ , $C_L = 50pF$ , $C_L = 100pF$ ,	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime. High temperatures degrade operating lifetimes. Operating lifetime is derated at temperatures greater than 105°C.

**Note 2:** All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.

**Note 3:** Maximum data rate is guaranteed by other measured parameters and is not tested directly.

**Note 4:** This IC includes overtemperature protection that is intended to protect the device during momentary overload conditions. Overtemperature protection activates at a junction temperature exceeding 150°C. Continuous operation above the specified maximum operating junction temperature may result in device degradation or failure.



## **TEST CIRCUITS**

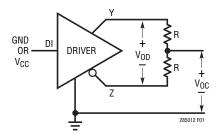


Figure 1. Driver DC Characteristics

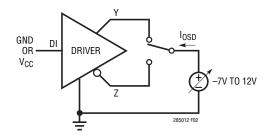


Figure 2. Driver Output Short-Circuit Current

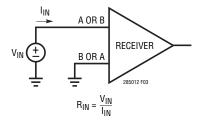


Figure 3. Receiver Input Current and Input Resistance

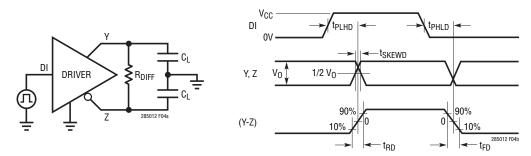


Figure 4. Driver Timing Measurement

## **TEST CIRCUITS**

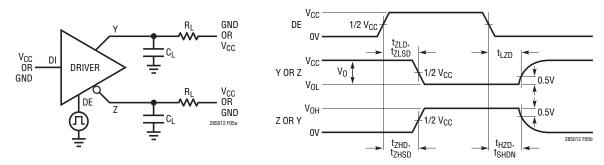


Figure 5. Driver Enable and Disable Timing Measurements

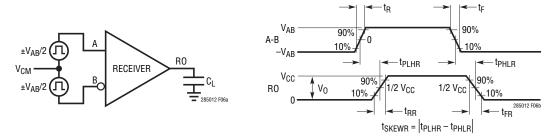


Figure 6. Receiver Propagation Delay Measurements

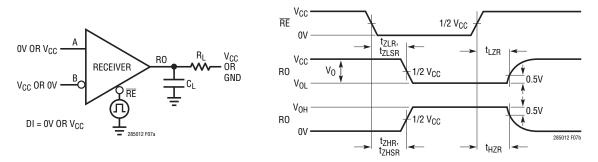
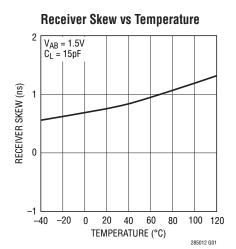
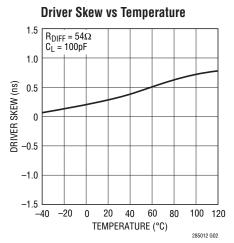


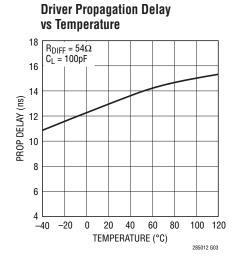
Figure 7. Receiver Enable/Disable Time Measurements

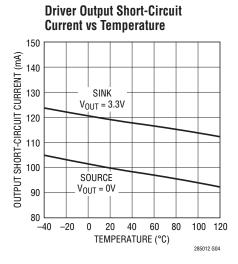


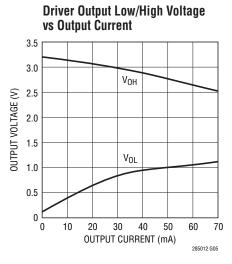
## TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^{\circ}C$ . $V_{CC} = 3.3V$ , unless otherwise noted.

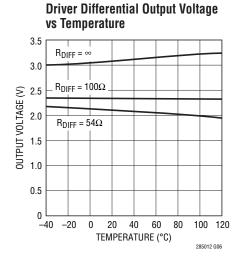


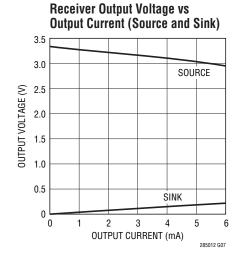


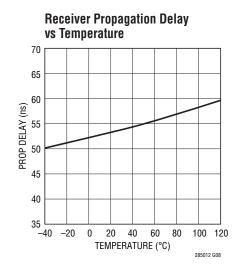


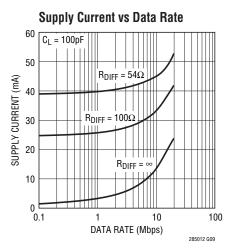














#### PIN FUNCTIONS

**R0:** Receiver Output. If the receiver output is enabled ( $\overline{RE}$  low) and A > B by 200mV, then RO will be high. If A < B by 200mV, then RO will be low. If the receiver inputs are open, shorted, or terminated without a valid signal, RO will be high.

**RE**: Receiver Enable. A low enables the receiver. A high input forces the receiver output into a high impedance state.

**DE:** Driver Enable. A high on DE enables the driver. A low input will force the driver outputs into a high impedance. If RE is high with DE low, the part will enter a low power shutdown state.

**DI:** Driver Input. If the driver outputs are enabled (DE high), then a low on DI forces the driver positive output low and negative output high. A high on DI, with the driver outputs enabled, forces the driver positive output high and negative output low.

GND: Ground.

**Y:** Noninverting Driver Output for LTC2851 and LTC2852. High impedance when driver disabled or unpowered.

**Z:** Inverting Driver Output for LTC2851 and LTC2852. High impedance when driver disabled or unpowered.

**A:** Noninverting Receiver Input (and Noninverting Driver Output for LTC2850). Impedance is  $>96k\Omega$  in receive mode or unpowered.

**B:** Inverting Receiver Input (and Inverting Driver Output for LTC2850). Impedance is  $>96k\Omega$  in receive mode or unpowered.

**V<sub>CC</sub>:** Positive Supply.  $3V \le V_{CC} \le 3.6V$ . Bypass with  $0.1\mu F$  ceramic capacitor.

**Exposed Pad:** Ground. The exposed pads on the DFN packages must be soldered to ground.

**NC:** Not connected internally for LTC2852 in SO-14 package.

#### **FUNCTION TABLES**

#### LTC2850

Logic	Inputs	Mode	A D	RO
DE	RE	Widue	A, B	nu
0	0	Receive	R <sub>IN</sub>	Driven
0	1	Shutdown	R <sub>IN</sub>	Hi-Z
1	0	Transceive	Driven	Driven
1	1	Transmit	Driven	Hi-Z

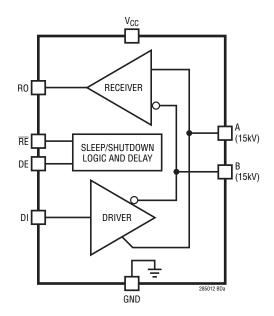
#### LTC2852

Logic	Inputs	Mode	A D	V 7	R0
DE	RE	Wione	A, B	Y, Z	nu
0	0	Receive	R <sub>IN</sub>	Hi-Z	Driven
0	1	Shutdown	R <sub>IN</sub>	Hi-Z	Hi-Z
1	0	Transceive	R <sub>IN</sub>	Driven	Driven
1	1	Transmit	R <sub>IN</sub>	Driven	Hi-Z

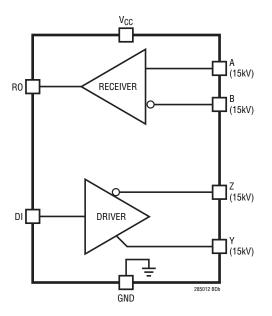


## **BLOCK DIAGRAM**

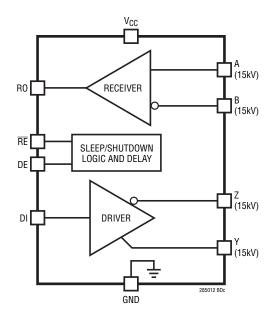
#### LTC2850



#### LTC2851



#### LTC2852





#### APPLICATIONS INFORMATION

#### Driver

The driver provides full RS485/RS422 compatibility. When enabled, if DI is high, Y-Z is positive for the full-duplex devices (LTC2851, LTC2852) and A-B is positive for the half-duplex device (LTC2850).

When the driver is disabled, both outputs are high impedance. For the full-duplex devices, the leakage on the driver output pins is guaranteed to be less than  $10\mu A$  over the entire common mode range of -7V to 12V. On the half-duplex LTC2850, the impedance is dominated by the receiver input resistance,  $R_{IN}$ .

#### **Driver Overvoltage and Overcurrent Protection**

The driver outputs are protected from short-circuits to any voltage within the Absolute Maximum range of  $(V_{CC} - 15V)$  to 15V. The typical peak current in this condition does not exceed 180mA.

If a high driver output is shorted to a voltage just above  $V_{CC}$ , a reverse current will flow into the supply. When this voltage exceeds  $V_{CC}$  by about 1.4V, the reverse current turns off. Preventing the driver from turning off with outputs shorted to output voltages just above  $V_{CC}$  keeps the driver active even for receiver loads that have a positive common mode with respect to the driver—a valid condition.

The worst-case peak reverse short-circuit current can be as high as 300mA in extreme cold conditions. If this current can not be absorbed by the supply, a 3.6V Zener diode can be added in parallel with the supply to sink this current.

All devices also feature thermal shutdown protection that disables the driver and receiver in case of excessive power dissipation (see Note 4 in the Electrical Characteristics section).

#### **Receiver and Failsafe**

With the receiver enabled, when the absolute value of the differential voltage between the A and B pins is greater than 200mV, the state of RO will reflect the polarity of (A-B)

These parts have a failsafe feature that guarantees the receiver output to be in a logic-high state when the inputs

are either shorted, left open, or terminated but not driven. This failsafe feature is guaranteed to work for inputs spanning the entire common mode range of -7V to 12V.

The receiver output is internally driven high (to  $V_{CC}$ ) or low (to ground) with no external pull-up needed. When the receiver is disabled the RO pin becomes Hi-Z with leakage of less than  $\pm 1\mu A$  for voltages within the supply range.

#### **Receiver Input Resistance**

The receiver input resistance from A or B to ground is guaranteed to be greater than 96k (C-, I-grade). This is 8x higher than the requirements for the RS485 standard and thus this receiver represents a one-eighth unit load. This, in turn, means that 8x the standard number of receivers, or 256 total, can be connected to a line without loading it beyond what is specified in the RS485 standard. The receiver input resistance from A or B to ground on high temperature H-grade parts is greater than 48k providing a one-quarter unit load. The high input resistance of the receiver is maintained whether it is enabled or disabled, powered or unpowered.

#### **Supply Current**

The unloaded static supply currents in these devices are very low, typically under  $500\mu A$  for all modes of operation. In applications with resistively terminated cables, the supply current is dominated by the driver load. For example, when using two  $120\Omega$  terminators with a differential driver output voltage of 2V, the DC load current is 33mA, which is sourced by the positive voltage supply. Power supply current increases with toggling data due to capacitive loading and this term can increase significantly at high data rates. Figure 13 shows supply current vs data rate for two different capacitive loads for the circuit configuration of Figure 4.

#### **High Speed Considerations**

A ground plane layout is recommended. A  $0.1\mu F$  bypass capacitor less than one-quarter inch away from the  $V_{CC}$  pin is also recommended. The PC board traces connected to signals A/B and Z/Y should be symmetrical and as short as possible to maintain good differential signal integrity.



#### APPLICATIONS INFORMATION

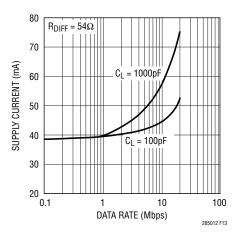


Figure 13. Supply Current vs Data Rate

To minimize capacitive effects, the differential signals should be separated by more than the width of a trace and should not be routed on top of each other if they are on different signal planes.

Care should be taken to route outputs away from any sensitive inputs to reduce feedback effects that might cause noise, jitter, or even oscillations. For example, in the full-duplex devices, DI and A/B should not be routed near the driver or receiver outputs.

The logic inputs have 150 mV of hysteresis to provide noise immunity. Fast edges on the outputs can cause glitches in the ground and power supplies which are exacerbated by capacitive loading. If a logic input is held near its threshold (typically 1.5V), a noise glitch from a driver transition may exceed the hysteresis levels on the logic and data input pins causing an unintended state change. This can be avoided by maintaining normal logic levels on the pins and by slewing inputs through their thresholds by faster than  $1V/\mu s$  when transitioning. Good supply decoupling and proper driver termination also reduce glitches caused by driver transitions.

#### Cable Length vs Data Rate

For a given data rate, the maximum transmission distance is bounded by the cable properties. A curve of cable length vs data rate compliant with the RS485/RS422 standards is shown in Figure 14. Three regions of this curve reflect different performance limiting factors in data transmission. In the flat region of the curve, maximum distance is determined by resistive losses in the cable. The downward sloping region represents limits in distance and data rate due to AC losses in the cable. The solid vertical line represents the specified maximum data rate in the RS485/RS422 standards. The dashed lines at 20Mbps show the maximum data rates of the LTC2850, LTC2851 and LTC2852.

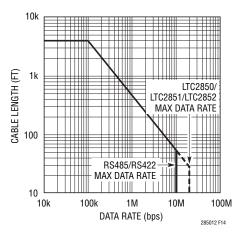
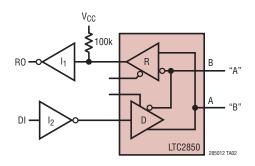


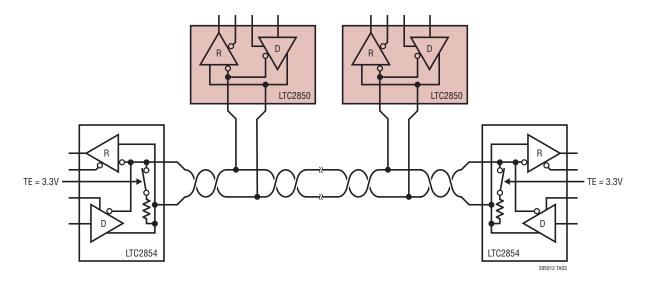
Figure 14. Cable Length vs Data Rate (RS485/RS422 Standard Shown in Solid Line)

## TYPICAL APPLICATIONS

Failsafe "0" Application (Idle State = Logic "0")



#### Multinode Network with End Termination Using the LTC2850 and LTC2854

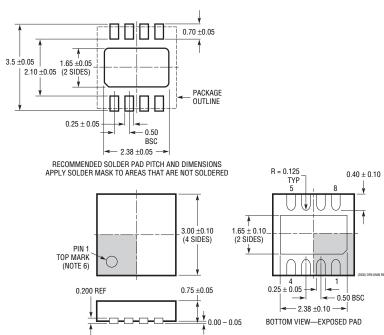


#### PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.

#### **DD Package** 8-Lead Plastic DFN (3mm × 3mm)

(Reference LTC DWG # 05-08-1698 Rev C)

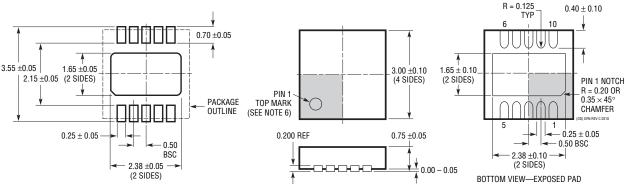


- NOTE
- 1. DRAWING TO BE MADE A JEDEC PACKAGE OUTLINE MO-229 VARIATION OF (WEED-1)

- 2. DRAWING NOT TO SCALE
  3. ALL DIMENSIONS ARE IN MILLIMETERS
  4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE
- MOLD FLASH, MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE 5. EXPOSED PAD SHALL BE SOLDER PLATED
- SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION
   ON TOP AND BOTTOM OF PACKAGE

#### **DD Package** 10-Lead Plastic DFN (3mm × 3mm)

(Reference LTC DWG # 05-08-1699 Rev C)



#### **RECOMMENDED** SOLDER PAD PITCH AND DIMENSIONS

- DRAWING TO BE MADE A JEDEC PACKAGE OUTLINE M0-229 VARIATION OF (WEED-2). CHECK THE LTC WEBSITE DATA SHEET FOR CURRENT STATUS OF VARIATION ASSIGNMENT 2. DRAWING NOT TO SCALE
- 3. ALL DIMENSIONS ARE IN MILLIMETERS

- 4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE
- MOLD FLASH. MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE
- 5. EXPOSED PAD SHALL BE SOLDER PLATED
  6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE



#### PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.

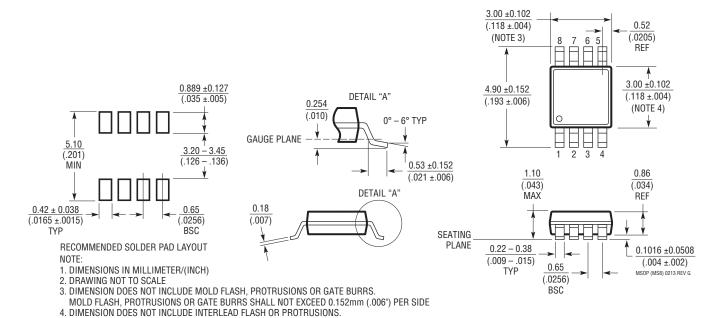
INTERLEAD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.152mm (.006") PER SIDE 5. LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.102mm (.004") MAX

4. DIMENSION DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.

INTERLEAD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.152mm (.006") PER SIDE 5. LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.102mm (.004") MAX

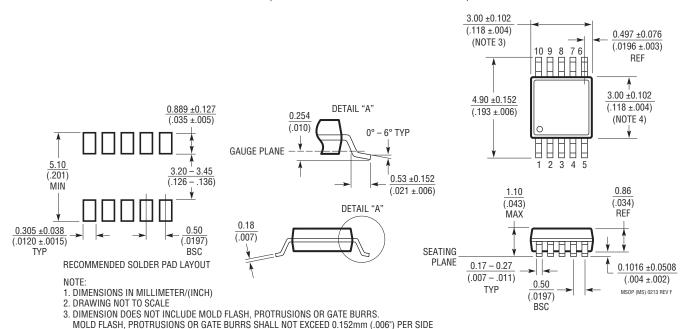
#### MS8 Package 8-Lead Plastic MSOP

(Reference LTC DWG # 05-08-1660 Rev G)



#### MS Package 10-Lead Plastic MSOP

(Reference LTC DWG # 05-08-1661 Rev F)



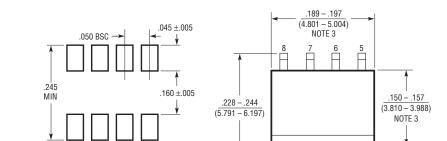
LINEAD TECHNOLOGY

.030 ±.005 TYP

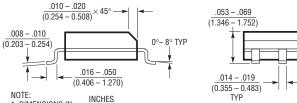
#### PACKAGE DESCRIPTION

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.

#### S8 Package 8-Lead Plastic Small Outline (Narrow .150 Inch) (Reference LTC DWG # 05-08-1610 Rev G)



RECOMMENDED SOLDER PAD LAYOUT



- 1. DIMENSIONS IN INCHES (MILLIMETERS)
- 2. DRAWING NOT TO SCALE

4. PIN 1 CAN BE BEVEL EDGE OR A DIMPLE

2. THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.

MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED .006" (0.15mm)

S08 REV G 0212

.004 – .010

(0.101 - 0.254)

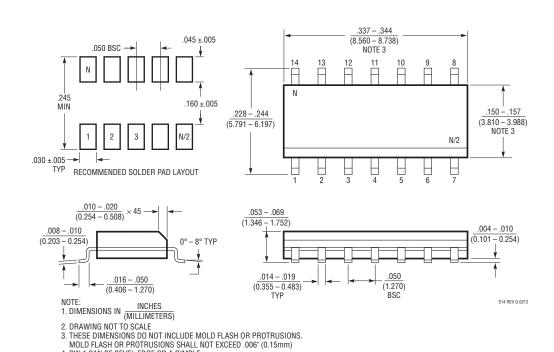
.050

 $(\overline{1.270})$ 

BSC

4. PIN 1 CAN BE BEVEL EDGE OR A DIMPLE

#### S Package 14-Lead Plastic Small Outline (Narrow .150 Inch) (Reference LTC DWG # 05-08-1610 Rev G)

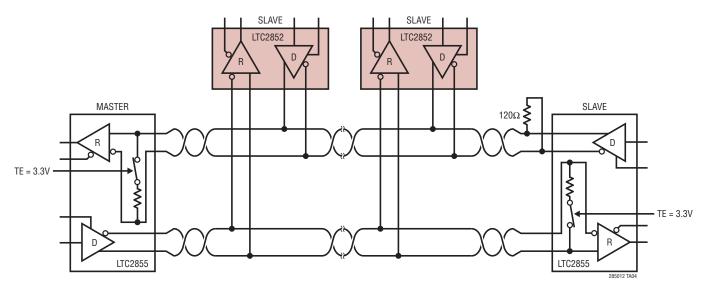


## **REVISION HISTORY** (Revision history begins at Rev D)

REV	DATE	DESCRIPTION	PAGE NUMBER
D	05/10	Added military grade parts	2, 3
Е	06/15	Added I <sub>OZD</sub> parameter for H-grade	4
		Updated Package descriptions	14 to 16



### TYPICAL APPLICATION



Full Duplex Network Using the LTC2852 and LTC2855

### **RELATED PARTS**

PART NUMBER	DESCRIPTION	COMMENTS
LTC485	Low Power RS485 Interface Transceiver	I <sub>CC</sub> = 300μA (Typ)
LTC491	Differential Driver and Receiver Pair	I <sub>CC</sub> = 300μA
LTC1480	3.3V Ultralow Power RS485 Transceiver	3.3V Operation
LTC1483	Ultralow Power RS485 Low EMI Transceiver	Controlled Driver Slew Rate
LTC1485	Differential Bus Transceiver	10Mbps Operation
LTC1487	Ultralow Power RS485 with Low EMI, Shutdown and High Input Impedance	Up to 256 Transceiver on the Bus
LTC1520	50Mbps Precision Quad Line Receiver	Channel-to-Channel Skew 400ps (Typ)
LTC1535	Isolated RS485 Full-Duplex Transceiver	2500V <sub>RMS</sub> Isolation in Surface Mount Package
LTC1685	52Mbps RS485 Transceiver with Precision Delay	Propagation Delay Skew 500ps (Typ)
LT1785	60V Fault Protected RS485 Transceiver	60V Tolerant, 15kV ESD
LTC2854/LTC2855	3.3V 20Mbps RS485/RS422 Transceivers with Integrated Switchable Termination	3.3V Operation, Integrated, Switchable, 120Ω Termination Resistor, 25kV ESD (LTC2854), 15kV ESD (LTC2855)
LTC2856-1	20Mbps and Slew Rate-Limited, 15kV RS485/RS422 Transceiver	15kV ESD
LTC2859/LTC2861	20Mbps RS485/RS422 Transceiver with Integrated Switchable Termination	Integrated, Switchable, $120\Omega$ Termination Resistor, 15kV ESD
LTC2862/LTC2865	±60V Fault Protected 3V to 5.5V RS485/RS422 Transceivers	20Mbps, Protected from Overvoltage Line Faults to ±60V, 15kV ESD
LTM°2881	Complete Isolated RS485/RS422 µModule® Transceiver + Power	2500V <sub>RMS</sub> Isolation in Surface Mount BGA or LGA